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Characterizing logic programming semantics with level mappings

Extended Abstract

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Abstract

Declarative semantics in logic programming and nonmonotonic reasoning are often defined via fixed points of semantic operators. While many relationships between different semantics known from the literature have been studied, a uniform treatment is still missing. In this paper, we provide uniform operator-free characterizations for some of the most important semantics, more precisely, for the stable, the well-founded, and the Fitting semantics, for the weakly-perfect model semantics, and for the least model semantics for negation-free programs.

1 Introduction

One of the very stimulating research questions in logic programming and nonmonotonic reasoning has been the search for an appropriate declarative understanding of negation. Several different semantics have been proposed, see e.g. [Sub99], each being more or less convincing, depending on one’s point of view, which may be that of a programmer, or motivated by common-sense reasoning. In this paper, we provide a uniform approach to some of the most important semantics: They will all be characterized by means of level mappings.

Level mappings are mappings from Herbrand bases to ordinals, i.e. they induce preorders on the set of all ground atoms while disallowing infinite
descending chains. They have been studied in termination analysis for logic programming, e.g. in [Bez89, AP93, Mar96], where they appear naturally, they have been used for defining classes of programs with desirable semantic properties, e.g. in [ABW88, Prz88, Cav91], they are intertwined with topological investigations of fixed-point semantics in logic programming, as studied e.g. in [Fit94, Sed95, Hit01, HS0x], and are relevant to some aspects of the study of relationships between logic programming and artificial neural networks [HKS99]. Our motivation, however, is quite different. We will employ level mappings in order to give uniform characterizations of different semantics.

Among the semantics based on classical two-valued logic, we will characterize the least model semantics for negation-free programs, and the stable model semantics; the latter result is due to [Fag94].

Among the semantics based on three-valued logics, the Fitting semantics [Fit85] and the well-founded semantics [VGRS91] are prominent and widely acknowledged choices. Theoretical relationships between them have been established, e.g. in [Fit02] by using lattice-based logic programming in four-valued logic, an approach which was recently extended in [DMT00]. The development of the weakly perfect model semantics, due to [PP90], was motivated by the intuition that recursion should be allowed through positive information, but not through negation. As such, it was developed out of the notion of stratification [ABW88, Prz88]. From the uniform characterizations of the Fitting semantics, the well-founded semantics, and the weakly perfect model semantics, which we will provide, it will be obvious that the well-founded semantics achieves this very goal in a much better way than the weakly perfect model semantics.

Proofs for the statements in this extended abstract have been omitted, and they can be found in the indicated literature. If no references are given, then the proofs are our own and can be found in [HW02]¹. We assume throughout, that the reader is familiar with the standard approaches to the semantics discussed in the sequel, as presented in the indicated literature.

2 Notation

A normal (logic) program is a finite set of (universally quantified) clauses of the form \( \forall (A \leftarrow A_1 \land \cdots \land A_n \land \neg B_1 \land \cdots \land \neg B_m) \), commonly written as \( A \leftarrow A_1, \ldots, A_n, \neg B_1, \ldots, \neg B_m \), where \( A \) and \( A_i \), for \( i = 1, \ldots, n \), are atoms, and \( \neg B_j \), for \( j = 1, \ldots, m \), are negated atoms, over some given first order

language. A is called the head of the clause, while the remaining literals, i.e. atoms and negated atoms, make up the body of the clause. A clause with empty body is called a unit clause or a fact. A clause is called definite, if it contains no negation symbols. A program is called definite if it consists only of definite clauses. We will usually denote atoms with A or B, and literals, which may be atoms or negated atoms, by L or K.

Given a logic program P, we can extract from it the components of a first order language. The corresponding set of ground atoms, i.e. the Herbrand base of the program, will be denoted by BP. The set of ground instances of P with respect to BP will be denoted by ground(P). A (three-valued or partial) interpretation I for P is a signed subset of BP, i.e. a subset of BP ∪ {¬A | A ∈ BP}, which is consistent, i.e. for each A ∈ BP at most one of A and ¬A is contained in I. We say that A is true with respect to (or in) I if A ∈ I, we say that A is false with respect to (or in) I if ¬A ∈ I, and if neither is the case, we say that A is undefined with respect to (or in) I. A body, i.e. a conjunction of literals, is true in an interpretation I if every literal in the body is true in I, it is false in I if one of its literals is false in I, and otherwise it is undefined in I. For a negated literal L = ¬A we will find it convenient to write ¬L ∈ I if A ∈ I. By IP we denote the set of all (three-valued) interpretations of P. It is a complete partial order (cpo) via set-inclusion, i.e. it contains the empty set as least element, and every ascending chain has a supremum, namely its union. A model of P is an interpretation I ∈ IP such that for each clause A ← A1, ..., An, ¬B1, ..., ¬Bm we have that I |= A1 ∧ ... ∧ An ∧ ¬B1 ∧ ... ∧ ¬Bm implies A ∈ I. A total interpretation is an interpretation I such that no A ∈ BP is undefined in I.

For an interpretation I and a program P, an I-partial level mapping for P is a partial mapping l : BP → α with domain dom(l) = {A | A ∈ I or ¬A ∈ I}, where α is some (countable) ordinal. We extend every level mapping to literals by setting l(¬A) = l(A) for all A ∈ dom(l). A (total) level mapping is a total mapping l : BP → α for some (countable) ordinal α.

3 Results

We first turn to definite programs. Recall, e.g. from [Llo88], that each definite program P has a distinguished least total Herbrand model, where least, in this context, refers to the ordering ≤t, usually considered on total interpretations, namely2 I ≤t K iff {A ∈ BP | A ∈ I} ⊆ {A ∈ BP | A ∈ K}. We call this model the definite model of P.

2The ordering ≤t is called the truth ordering in [Fit02], while subset inclusion on signed subsets of BP is called the knowledge ordering.
3.1 **Theorem** Let \( P \) be a definite program. Then there exists a unique total model \( M \) of \( P \) for which there exists a (total) level mapping \( l : B_P \to \alpha \) such that for each \( A \in B_P \) with \( A \in M \) there exists \( A \leftarrow A_1, \ldots, A_n \) in \( \text{ground}(P) \) with \( A_i \in M \) and \( l(A) \geq l(A_i) \) for all \( i \). Furthermore, \( M \) coincides with the definite model of \( P \).

The proof of Theorem 3.1 is straightforward using the fact that the definite model can be obtained as the supremum, with respect to the truth ordering, of iterates of the monotonic immediate consequence operator \( T_P \) associated with the program \( P \), see [Llo88]. The level \( l(A) \) of an atom \( A \) corresponds to the least integer \( k \) with \( A \in T_P \uparrow(k + 1) \).

In order to avoid confusion, we remark that for the remainder of this paper, interpretations are three-valued and the order which is considered is always subset inclusion on signed subsets of \( B_P \).

For semantics of normal logic programs, one of the most popular approaches is based on the so-called *stable models*, introduced in [GL88], which are tightly connected to a reading of logic programs in Reiter’s *default logic* [Rei80].

3.2 **Theorem** Let \( P \) be a normal program. A total model \( M \) of \( P \) is stable if and only if there exists a level mapping \( l : B_P \to \alpha \) such that for each \( A \in B_P \) with \( A \in M \) there exists \( A \leftarrow A_1, \ldots, A_n, \neg B_1, \ldots, \neg B_m \) in \( \text{ground}(P) \) with \( A_i \in M \), \( \neg B_j \in M \), and \( l(A) \geq l(A_i) \) for all \( i \) and \( j \).

Theorem 3.2 is due to [Fag94], building on a result in [DK89]. The latter was recently generalized in [Wen02b].

We next turn to partial interpretations. One of the earliest and fundamental approaches was presented in [Fit85]: A distinguished three-valued model is associated with any given normal program \( P \). This model was originally called the *Kripke-Kleene model* of \( P \), and is recently often called the *Fitting model* of \( P \).

3.3 **Theorem** Let \( P \) be a normal program. Then there exists a greatest model \( M \) of \( P \) with the property that there is an \( M \)-partial level mapping \( l \) for \( P \) such that each \( A \in \text{dom}(l) \) satisfies one of the following conditions.

\[ \text{(Fi)} \quad A \in M \text{ and there exists } A \leftarrow L_1, \ldots, L_n \text{ in } P \text{ such that for all } i \text{ we have } L_i \in M \text{ and } l(A) > l(L_i). \]

\[ \text{(Fii)} \quad \neg A \in M \text{ and for each } A \leftarrow L_1, \ldots, L_n \text{ in } P \text{ there exists } i \text{ with } \neg L_i \in M \text{ and } l(A) > l(L_i). \]

Furthermore, \( M \) coincides with the Fitting model of \( P \).
The main idea of the proof of Theorem 3.3, as presented in [HW02], is that the level \( l(A) \) of an atom \( A \) corresponds to the least ordinal \( \alpha \) such that \( A \) is not undefined in \( \Phi_P \uparrow (\alpha + 1) \), where \( \Phi_P \) is the monotonic operator from [Fit85] whose least fixed point is the Fitting model of \( P \).

A less skeptical semantics than the Fitting semantics is that based on the notion of weakly perfect model, as presented in [PP90]. In this approach, a rather involved construction assigns a unique three-valued model to each given program. The driving intuition behind the construction was the idea that recursion should be allowed through positive dependencies while being restricted through negation. From this perspective, it is a generalization of the perfect model semantics for locally stratified [Prz88] and stratified [ABW88] programs.

### 3.4 Theorem

Let \( P \) be a normal program. Then there exists a greatest model \( M \) of \( P \) with the property that there is an \( M \)-partial level mapping \( l \) for \( P \) such that each \( A \in \text{dom}(l) \) satisfies one of the following conditions.

(WSi) \( A \in M \) and there exists \( A \leftarrow L_1, \ldots, L_n \) in \( \text{ground}(P) \) such that for all \( i \) we have \( L_i \in M \) and \( l(A) > l(L_i) \).

(WSii) \( \neg A \in M \) and for each \( A \leftarrow A_1, \ldots, A_n, \neg B_1, \ldots, \neg B_m \) in \( P \) one of the following holds:

(WSiia) There exists \( i \) with \( \neg A_i \in M \) and \( l(A) > l(A_i) \).

(WSiib) For all \( k \) we have \( l(A) \geq l(A_k) \), for all \( j \) we have \( l(A) > l(B_j) \), and there exists \( i \) with \( \neg A_i \in I \).

(WSiic) There exists \( j \) with \( B_j \in M \) and \( l(A) > l(B_j) \).

Furthermore, \( M \) coincides with the (partial) weakly perfect model of \( P \).

It shall be noted that Theorem 3.4 refers to a slightly different notion of (partial) weakly perfect model, than the one originally presented in [PP90], but the adjustments made in the definition seem to be rather reasonable, and this is discussed in [HW02]. The proof is very technical, and was basically developed in [Wen02a].

We finally turn to the well-founded semantics. In this approach, again, a distinguished three-valued model is assigned to each given program \( P \), called the well-founded model of \( P \), and introduced in [VGRS91]. It is tightly related to the stable model semantics [Gel89, Prz89].

### 3.5 Theorem

Let \( P \) be a normal program. Then there exists a greatest model \( M \) of \( P \) with the property that there is an \( M \)-partial level mapping \( l \) for \( P \) such that each \( A \in \text{dom}(l) \) satisfies one of the following conditions.
(WFi) \( A \in M \) and there exists \( A \leftarrow L_1, \ldots, L_n \) in \( \text{ground}(P) \) such that for all \( i \) we have \( L_i \in M \) and \( l(A) > l(L_i) \).

(WFii) \( \neg A \in M \) and for each \( A \leftarrow A_1, \ldots, A_n, \neg B_1, \ldots, \neg B_m \) in \( P \)

one of the following holds:

(WFiiia) There exists \( i \) with \( \neg A_i \in M \) and \( l(A) \geq l(A_i) \).

(WFiiib) There exists \( j \) with \( B_j \in M \) and \( l(A) > l(B_j) \).

Furthermore, \( M \) coincides with the well-founded model of \( P \).

Theorem 3.5 is proven along the same lines as Theorem 3.3, replacing the
operator \( \Phi_P \) by \( W_P \), as introduced in [VGRS91].

Considering that the main motivation for the introduction of the weakly perfect model semantics was to restrict recursion through negation, we notice by comparing conditions (WSii) and (WFii), that the well-founded semantics provides a much cleaner and more convincing way of achieving this.

We remark that conditions (Fi), (WSi) and (WFi) are identical. Indeed, replacing (WFi) by a “stratified” version such as the following is not satisfactory.

(SFi) \( A \in M \) and there exists a clause \( A \leftarrow A_1, \ldots, A_n, \neg B_1, \ldots, \neg B_m \) in \( \text{ground}(P) \) such that \( A_i, \neg B_j \in M \), \( l(A) \geq l(A_i) \), and \( l(A) > l(B_j) \)
for all \( i \) and \( j \).

If we replace condition (WFi) by condition (SFi), then it is not guaranteed that for any given program there is a greatest model satisfying the desired properties: Consider the program consisting of the two clauses \( p \leftarrow p \) and \( q \leftarrow \neg p \), and the two (total) models \( \{p, \neg q\} \) and \( \{\neg p, q\} \), which are incomparable, and the level mapping \( l \) with \( l(p) = 0 \) and \( l(q) = 1 \).

The characterization of the well-founded model in Theorem 3.5 contrasts nicely with another characterization which can be found in [LMPS95], as follows.

### 3.6 Theorem

The well-founded model of a program \( P \) is the least three-valued model \( M \) of \( P \) such that there exists a (total) level mapping \( l \) for \( P \) with the property that for each \( A \in B_P \) with \( \neg A \not\in M \) there exists a clause \( A \leftarrow A_1, \ldots, A_n, \neg B_1, \ldots, \neg B_m \) in \( \text{ground}(P) \) with \( l(A) > l(A_i) \) and \( \neg A_i \not\in M \) for all \( i \), and \( B_j \not\in M \) for all \( j \).

Theorem 3.6 characterizes the well-founded model \( M \) by means of conditions on all atoms which are not false in \( M \), while Theorem 3.5 characterizes it by means of conditions on all atoms which are not undefined in \( M \).
4 Conclusions

We have presented uniform characterizations, using level mappings, of some of the most important semantics for logic programs. The uniformity of the presentation allows for an easy comparison of the different approaches. Our characterization of the well-founded model, for example, exhibits the close relationship, in spirit, between the well-founded semantics and the idea underlying the notion of stratification, thus providing further evidence that the well-founded semantics is a particularly important one. Also, the following theorem follows immediately from our uniform characterizations.

4.1 Theorem Let $P$ be a normal program with Fitting model $M_f$, weakly perfect model $M_p$, and well-founded model $M_w$. Then $M_f \subseteq M_p \subseteq M_w$.

We believe that our approach should be applicable to most fixed-point semantics based on monotonic operators. In particular, it should be possible to employ our methods in order to characterize different forms of well-founded semantics for (extended) disjunctive logic programs, see e.g. [LRS97], and also to the study of fixed-point semantics of logic programming in algebraic domains, as put forward in [RZ01, Hit02].

References


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